

# Euler symmetric parameters

We verified that the Euler angle-axis representation and the Euler angles representation have singularities. Now, we will see a representation that has no singularity, but requires 4 parameters.

Let  $\mathcal{F}_a$  and  $\mathcal{F}_b$  be two coordinate systems in which the Euler angle-axis is  $(\underline{v}, \theta)$ . Thus, the Euler symmetric parameters (also called Rodrigues symmetric parameters) are defined as follows:

$$\underline{\epsilon} = \frac{\underline{v}}{2} \sin \frac{\theta}{2} \longrightarrow \text{Gibbs / Rodrigues vector}$$

$$\eta = \cos \frac{\theta}{2}$$

Notice that all information in the Euler axis-angle is embedded in these two parameters. Furthermore, we have the following property:

$$\underline{\epsilon}^T \underline{\epsilon} + \eta^2 = \frac{\underline{v}^T \underline{v}}{4} \frac{\sin^2 \frac{\theta}{2}}{2} + \frac{\cos^2 \frac{\theta}{2}}{2} = \frac{\sin^2 \frac{\theta}{2}}{2} + \frac{\cos^2 \frac{\theta}{2}}{2} = 1$$

$$\underline{\epsilon}^T \underline{\epsilon} + \eta^2 = 1$$

These parameters can be related to the DCM as follows:

$$\begin{aligned} C_{ba} &= \cos \theta \mathbb{I}_3 + (1 - \cos \theta) \underline{v} \underline{v}^T - \sin \theta \underline{v}^\times \\ &= \left[ 2 \cos^2 \frac{\theta}{2} - 1 \right] \mathbb{I}_3 + \left[ 1 + 1 - 2 \cos^2 \frac{\theta}{2} \right] \underline{v} \underline{v}^T - 2 \frac{\sin \theta}{2} \frac{\cos \theta}{2} \underline{v}^\times \longrightarrow \cos \theta = 2 \cos^2 \frac{\theta}{2} - 1 \quad \sin \theta = 2 \frac{\sin \theta}{2} \frac{\cos \theta}{2} \\ &= \left[ 2 \cos^2 \frac{\theta}{2} - 1 \right] \mathbb{I}_3 + 2 \left[ \frac{1 - \cos^2 \frac{\theta}{2}}{2} \right] \underline{v} \underline{v}^T - 2 \frac{\cos \theta}{2} \frac{\sin \theta}{2} \underline{v}^\times \\ 2\eta^2 - 1 &= 2\eta^2 - \underline{\epsilon}^T \underline{\epsilon} - \eta^2 = \eta^2 - \underline{\epsilon}^T \underline{\epsilon} \quad \frac{\sin^2 \frac{\theta}{2}}{2} \quad \left[ \frac{\sin \theta}{2} \frac{\underline{v}}{2} \right]^\times \\ &= \left[ 2 \cos^2 \frac{\theta}{2} - 1 \right] \mathbb{I}_3 + 2 \frac{\sin^2 \frac{\theta}{2}}{2} \underline{v} \underline{v}^T - 2 \frac{\cos \theta}{2} \left[ \frac{\sin \theta}{2} \frac{\underline{v}}{2} \right]^\times \end{aligned}$$

$$\Rightarrow C_{ba} = (\eta^2 - \underline{\epsilon}^T \underline{\epsilon}) \mathbb{I}_3 + 2 \underline{\epsilon} \underline{\epsilon}^T - 2 \eta \underline{\epsilon}^\times$$

## Composition of rotations

Let  $(\underline{\epsilon}_1, \eta_1)$  be the Euler symmetric parameters that describe the rotation from  $\mathcal{F}_a$  to  $\mathcal{F}_b$ . Let  $(\underline{\epsilon}_2, \eta_2)$  be the Euler symmetric parameters that describe the rotation from  $\mathcal{F}_b$  to  $\mathcal{F}_c$ . We want to find the Euler symmetric parameters that describe the rotation from  $\mathcal{F}_a$  to  $\mathcal{F}_c$  in terms of  $\underline{\epsilon}_1, \eta_1, \underline{\epsilon}_2,$  and  $\eta_2$ .

From the Euler angle-axis theory, if  $\sin \theta_3 \neq 0$ , then:

$$\cos \frac{\theta_3}{2} = \cos \frac{\theta_1}{2} \cos \frac{\theta_2}{2} - \frac{\sin \theta_1}{2} \frac{\sin \theta_2}{2} \underline{v}_1^T \underline{v}_2$$

$$\underline{v}_3 \sin \frac{\theta_3}{2} = \underline{v}_1 \sin \frac{\theta_1}{2} \cos \frac{\theta_2}{2} + \underline{v}_2 \sin \frac{\theta_2}{2} \cos \frac{\theta_1}{2} + \underline{v}_1^\times \underline{v}_2 \sin \frac{\theta_1}{2} \frac{\sin \theta_2}{2}$$

Thus:

$$\cos \frac{\Theta_3}{2} = \eta_3 = \cos \frac{\Theta_1}{2} \cos \frac{\Theta_2}{2} - \left[ \frac{\underline{v}_1 \sin \frac{\Theta_1}{2}}{2} \right]^T \left[ \frac{\underline{v}_2 \sin \frac{\Theta_2}{2}}{2} \right]$$

$$\Rightarrow \eta_3 = \eta_1 \eta_2 - \underline{e}_1^T \underline{e}_2$$

$$\frac{\underline{v}_3 \sin \frac{\Theta_3}{2}}{2} = \underline{e}_3 = \left[ \frac{\underline{v}_1 \sin \frac{\Theta_1}{2}}{2} \right] \cos \frac{\Theta_2}{2} + \left[ \frac{\underline{v}_2 \sin \frac{\Theta_2}{2}}{2} \right] \cos \frac{\Theta_1}{2} + \left[ \frac{\underline{v}_1 \sin \frac{\Theta_1}{2}}{2} \right]^{\times} \left[ \frac{\underline{v}_2 \sin \frac{\Theta_2}{2}}{2} \right]$$

$$\Rightarrow \underline{e}_3 = \eta_2 \underline{e}_1 + \eta_1 \underline{e}_2 + \underline{e}_1^{\times} \underline{e}_2$$

If  $\Theta_3 = 180^\circ$ , then

$$\eta_3 = 0 \quad \text{and} \quad \underline{e}_3 = \underline{v}_3 \quad \longrightarrow \quad \eta_1 \eta_2 = \underline{e}_1^T \underline{e}_2 = \underline{e}_2^T \underline{e}_1$$

Thus:

$$\underline{C}_{ca} = 2\underline{v}_3 \underline{v}_3^T - \underline{I}_3 = 2 \underline{e}_3 \underline{e}_3^T - \underline{I}_3$$

Suppose that we can also write  $\underline{e}_3 = \eta_2 \underline{e}_1 + \eta_1 \underline{e}_2 + \underline{e}_1^{\times} \underline{e}_2$ . In this case:

$$\underline{C}_{ca} = 2 \left[ \eta_2 \underline{e}_1 + \eta_1 \underline{e}_2 + \underline{e}_1^{\times} \underline{e}_2 \right] \left[ \eta_2 \underline{e}_1 + \eta_1 \underline{e}_2 + \underline{e}_1^{\times} \underline{e}_2 \right]^T - \underline{I}_3$$

$$= 2 \left[ \eta_2 \underline{e}_1 + \eta_1 \underline{e}_2 + \underline{e}_1^{\times} \underline{e}_2 \right] \left[ \eta_2 \underline{e}_1^T + \eta_1 \underline{e}_2^T - \underline{e}_2^T \underline{e}_1^{\times} \right] - \underline{I}_3$$

$$= 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + \underbrace{\eta_1 \eta_2}_{\underline{e}_1^T \underline{e}_2} \underline{e}_1 \underline{e}_2^T - \eta_2 \underline{e}_1 \underline{e}_2^T \underline{e}_1^{\times} + \underbrace{\eta_1 \eta_2}_{\underline{e}_2^T \underline{e}_1} \underline{e}_2 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T - \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} + \eta_2 \underline{e}_1^{\times} \underline{e}_2 \underline{e}_1^T + \eta_1 \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T - \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} \right] - \underline{I}_3$$

$$= 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + \underline{e}_1 \underline{e}_1^T \underline{e}_2 \underline{e}_2^T - \eta_2 \underline{e}_1 \underline{e}_2^T \underline{e}_1^{\times} + \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T - \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} + \eta_2 \underline{e}_1^{\times} \underline{e}_2 \underline{e}_1^T + \eta_1 \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T - \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} + \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} - \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} \right] - \underline{I}_3$$

↳ Using that:  $\underline{m} \underline{u}^{\times} + \underline{u}^{\times} \underline{m}^T = \text{tr}[\underline{m}] \underline{u}^{\times} - [\underline{m}^T \underline{u}]^{\times}$ ,  $\underline{u} \in \mathbb{R}^3$ ,  $\underline{m} \in \mathbb{R}^{3 \times 3}$ , then:

$$\eta_1 \left[ \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T + \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} \right] = \eta_1 \left[ \text{tr}[\underline{e}_2 \underline{e}_2^T] \underline{e}_1^{\times} - \underbrace{[\underline{e}_2 \underline{e}_2^T \underline{e}_1]^{\times}}_{\text{scalar}} \right]$$

$$\text{Since } \text{tr}[\underline{e}_2 \underline{e}_2^T] = \text{tr} \begin{bmatrix} e_{2,x}^2 & \cdot & \cdot \\ \cdot & e_{2,y}^2 & \cdot \\ \cdot & \cdot & e_{2,z}^2 \end{bmatrix} = e_{2,x}^2 + e_{2,y}^2 + e_{2,z}^2 = \underline{e}_2^T \underline{e}_2, \text{ then:}$$

$$\eta_1 \left[ \underline{e}_1^{\times} \underline{e}_2 \underline{e}_2^T + \underline{e}_2 \underline{e}_2^T \underline{e}_1^{\times} \right] = \eta_1 \left[ \underline{e}_2^T \underline{e}_2 \underline{e}_1^{\times} - \underline{e}_2^T \underline{e}_1 \underline{e}_2^{\times} \right]$$

$$C_{ca} = 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + \underline{e}_1 \underline{e}_1^T \underline{e}_2 \underline{e}_2^T - \eta_2 \underline{e}_1 \underline{e}_2^T \underline{e}_1^x + \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T - 2 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right. \\ \left. + \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_1^T + \eta_1 \underline{e}_2^T \underline{e}_2 \underline{e}_1^x - \eta_1 \underline{e}_2^T \underline{e}_1 \underline{e}_2^x - \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x - \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_2^T + \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_1^T \right] - \mathbb{I}_3$$

↳ Using that:  $\underline{m} \underline{u}^x + \underline{u}^x \underline{m}^T = \text{tr}[\underline{m}] \underline{u}^x - [\underline{m}^T \underline{u}]^x$ ,  $\underline{u} \in \mathbb{R}^3$ ,  $\underline{m} \in \mathbb{R}^{3 \times 3}$ , then:

$$-\eta_2 \left[ \overbrace{\underline{e}_1 \underline{e}_2^T \underline{e}_1^x}^{\underline{m}} + \overbrace{\underline{e}_1^x \underline{e}_2 \underline{e}_1^T}^{\underline{m}^T} \right] = -\eta_2 \left[ \text{tr}[\underline{e}_1 \underline{e}_2^T] \underline{e}_1^x - \underbrace{[\underline{e}_2 \underline{e}_1^T \underline{e}_1]^x}_{\text{scalar}} \right]$$

$$\text{Since } \text{tr}[\underline{e}_1 \underline{e}_2^T] = \text{tr} \begin{bmatrix} \underline{e}_{1,x} \underline{e}_{2,x} & \cdot & \cdot \\ \cdot & \underline{e}_{1,y} \underline{e}_{2,y} & \cdot \\ \cdot & \cdot & \underline{e}_{1,z} \underline{e}_{2,z} \end{bmatrix} = \underline{e}_{1,x} \underline{e}_{2,x} + \underline{e}_{1,y} \underline{e}_{2,y} + \underline{e}_{1,z} \underline{e}_{2,z} = \underline{e}_1^T \underline{e}_2, \text{ then:}$$

$$-\eta_2 [\underline{e}_1 \underline{e}_2^T \underline{e}_1^x + \underline{e}_1^x \underline{e}_2 \underline{e}_1^T] = -\eta_2 [\underline{e}_1^T \underline{e}_2 \underline{e}_1^x - \underline{e}_1^T \underline{e}_1 \underline{e}_2^x]$$

$$C_{ca} = 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + \underline{e}_1 \underline{e}_1^T \underline{e}_2 \underline{e}_2^T + 2 \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_1^T + \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T - 2 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right. \\ \left. - \eta_2 \overbrace{\underline{e}_1^T \underline{e}_2 \underline{e}_1^x}^{\eta_1 \eta_2} + \eta_2 \underline{e}_1^T \underline{e}_1 \underline{e}_2^x + \eta_1 \overbrace{\underline{e}_2^T \underline{e}_2 \underline{e}_1^x}^{\eta_1 \eta_2} - \eta_1 \underline{e}_2^T \underline{e}_1 \underline{e}_2^x - \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right] - \mathbb{I}_3$$

$$C_{ca} = 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + \underline{e}_1 \underline{e}_1^T \underline{e}_2 \underline{e}_2^T + 2 \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_1^T + \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T - 2 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right. \\ \left. - \eta_1 (\eta_2^2 - \underline{e}_2^T \underline{e}_2) \underline{e}_1^x - \eta_2 (\eta_1^2 - \underline{e}_1^T \underline{e}_1) \underline{e}_2^x - \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right] - \mathbb{I}_3 =$$

↳ Using that  $\underline{u}^x \underline{v}^x - \underline{v}^x \underline{u}^x = \underline{v} \underline{u}^T - \underline{u} \underline{v}^T$ ,  $\underline{u}, \underline{v} \in \mathbb{R}^3$ , then:

$$\underline{e}_1 \underline{e}_1^T \underline{e}_2 \underline{e}_2^T + \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T = \underline{e}_1^T \underline{e}_2 \left[ \overbrace{\underline{e}_1 \underline{e}_2^T}^{\underline{v}} + \overbrace{\underline{e}_2 \underline{e}_1^T}^{\underline{u}^T} - \overbrace{\underline{e}_2 \underline{e}_1^T}^{\underline{u}} + \overbrace{\underline{e}_1 \underline{e}_2^T}^{\underline{v}^T} \right] = \\ \underline{e}_1^T \underline{e}_2 \left[ \overbrace{\underline{e}_2^x \underline{e}_1^x}^{\underline{v}^x} - \overbrace{\underline{e}_1^x \underline{e}_2^x}^{\underline{u}^x} + 2 \underline{e}_2 \underline{e}_1^T \right] = \underline{e}_1^T \underline{e}_2 \underline{e}_2^x \underline{e}_1^x - \underline{e}_1^T \underline{e}_2 \underline{e}_1^x \underline{e}_2^x + 2 \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T$$

$$C_{ca} = 2 \left[ \eta_2^2 \underline{e}_1 \underline{e}_1^T + 2 \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \underline{e}_1^T \underline{e}_2 \underline{e}_2^x \underline{e}_1^x - \underline{e}_1^T \underline{e}_2 \underline{e}_1^x \underline{e}_2^x + 2 \eta_2 \underline{e}_1^x \underline{e}_2 \underline{e}_1^T + \eta_1^2 \underline{e}_2 \underline{e}_2^T \right. \\ \left. - 2 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x - \eta_1 (\eta_2^2 - \underline{e}_2^T \underline{e}_2) \underline{e}_1^x - \eta_2 (\eta_1^2 - \underline{e}_1^T \underline{e}_1) \underline{e}_2^x - \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \right] - \mathbb{I}_3$$

↳ Using that  $\underline{u}^x \underline{v}^x = \underline{v} \underline{u}^T - \underline{v}^T \underline{u} \mathbb{I}_3$ , then

$$-\underline{e}_1^T \underline{e}_2 \overbrace{\underline{e}_1^x \underline{e}_2^x}^{\underline{u}^x \underline{v}^x} = -\overbrace{\underline{e}_1^T \underline{e}_2}^{\eta_1 \eta_2} \left[ \underline{e}_2 \underline{e}_1^T - \overbrace{\underline{e}_2^T \underline{e}_1}^{\eta_1 \eta_2} \mathbb{I}_3 \right] = -\underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \eta_1^2 \eta_2^2 \mathbb{I}_3$$

$$C_{ca} = 2 \left[ \eta_1^2 \eta_2^2 \mathbb{I}_3 + \eta_2^2 \underline{e}_1 \underline{e}_1^T + 2 \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + \overbrace{\underline{e}_1^T \underline{e}_2}^{\eta_1 \eta_2} \underline{e}_2^x \underline{e}_1^x + \eta_1^2 \underline{e}_2 \underline{e}_2^T + 2 \eta_2 \overbrace{\underline{e}_1^x \underline{e}_2 \underline{e}_1^T}^{-\underline{e}_2^T \underline{e}_1} \right. \\ \left. - 2 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x - \eta_1 (\eta_2^2 - \underline{e}_2^T \underline{e}_2) \underline{e}_1^x - \eta_2 (\eta_1^2 - \underline{e}_1^T \underline{e}_1) \underline{e}_2^x - \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x - \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T \right] - \mathbb{I}_3$$

$$C_{ca} = 2 \eta_1^2 \eta_2^2 \mathbb{I}_3 + 2 \eta_2^2 \underline{e}_1 \underline{e}_1^T + 4 \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T + 2 \eta_1 \eta_2 \underline{e}_2^x \underline{e}_1^x + 2 \eta_1^2 \underline{e}_2 \underline{e}_2^T - 4 \eta_2 \overbrace{\underline{e}_2^x \underline{e}_1 \underline{e}_1^T} \\ - 4 \eta_1 \underline{e}_2 \underline{e}_2^T \underline{e}_1^x - 2 \eta_1 (\eta_2^2 - \underline{e}_2^T \underline{e}_2) \underline{e}_1^x - 2 \eta_2 (\eta_1^2 - \underline{e}_1^T \underline{e}_1) \underline{e}_2^x - 2 \underline{e}_1^x \underline{e}_2 \underline{e}_2^T \underline{e}_1^x \\ - 2 \underline{e}_2 \underline{e}_2^T \underline{e}_1 \underline{e}_1^T - \mathbb{I}_3$$



Notice that:

$$\vec{v}^x \vec{v}^x = \vec{v} \vec{v}^T - \vec{v}^T \vec{v} \mathbb{I}_3$$

$$-2\eta_1 \eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1 = -2\eta_1 \eta_2 \left[ \underline{\underline{e}}_1 \underline{\underline{e}}_2^T - \overbrace{\underline{\underline{e}}_1^T \underline{\underline{e}}_2}^{\eta_1 \eta_2} \mathbb{I}_3 \right] = -2\eta_1 \eta_2 \underline{\underline{e}}_1 \underline{\underline{e}}_2^T + 2\eta_1^2 \eta_2^2 \mathbb{I}_3$$

$$\begin{aligned} C_{ca} &= 2(\eta_1^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1 \underline{\underline{e}}_1^T + 4 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1 \underline{\underline{e}}_1^T + 4\eta_1 \eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1^x + 2(\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \underline{\underline{e}}_2 \underline{\underline{e}}_2^T - 4\eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1 \underline{\underline{e}}_1^T \\ &\quad - 4\eta_1 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1^x - 2\eta_1 (\eta_1^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1^x - 2\eta_2 (\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \underline{\underline{e}}_2^x + 2 \underline{\underline{e}}_1 \underline{\underline{e}}_1^T \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \\ &\quad + \left( 2 \underline{\underline{e}}_2^T \underline{\underline{e}}_2 \underline{\underline{e}}_1^T \underline{\underline{e}}_1 - 1 \right) \mathbb{I}_3 - 2\eta_1 \eta_2 \underline{\underline{e}}_1 \underline{\underline{e}}_2^T + 2\eta_1^2 \eta_2^2 \mathbb{I}_3 \end{aligned}$$

$$\begin{aligned} C_{ca} &= 2(\eta_1^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1 \underline{\underline{e}}_1^T + 4 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1 \underline{\underline{e}}_1^T + 4\eta_1 \eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1^x + 2(\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \underline{\underline{e}}_2 \underline{\underline{e}}_2^T - 4\eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1 \underline{\underline{e}}_1^T \\ &\quad - 4\eta_1 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1^x - 2\eta_1 (\eta_1^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1^x - 2\eta_2 (\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \underline{\underline{e}}_2^x + \\ &\quad + \left( 2\eta_1^2 \eta_2^2 + 2 \underline{\underline{e}}_2^T \underline{\underline{e}}_2 \underline{\underline{e}}_1^T \underline{\underline{e}}_1 - 1 \right) \mathbb{I}_3 \end{aligned}$$

Notice that:

$$\begin{aligned} 2\eta_1^2 \eta_2^2 + 2 \underline{\underline{e}}_2^T \underline{\underline{e}}_2 \underline{\underline{e}}_1^T \underline{\underline{e}}_1 - 1 &= \eta_1^2 \eta_2^2 + \eta_1^2 \overbrace{\eta_2^2}^{1 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2} + \overbrace{\underline{\underline{e}}_2^T \underline{\underline{e}}_2}^{1 - \eta_2^2} \underline{\underline{e}}_1^T \underline{\underline{e}}_1 + \underline{\underline{e}}_2^T \underline{\underline{e}}_2 \underline{\underline{e}}_1^T \underline{\underline{e}}_1 - 1 \\ &= \eta_1^2 \eta_2^2 + \eta_1^2 - \eta_1^2 \underline{\underline{e}}_2^T \underline{\underline{e}}_2 + \underline{\underline{e}}_2^T \underline{\underline{e}}_2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1 \eta_2^2 + \underline{\underline{e}}_2^T \underline{\underline{e}}_2 \underline{\underline{e}}_1^T \underline{\underline{e}}_1 - 1 \\ &= (\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) (\eta_2^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \end{aligned}$$

$$\begin{aligned} C_{ca} &= (\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) (\eta_2^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \mathbb{I}_3 + 2(\eta_1^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1 \underline{\underline{e}}_1^T - 2\eta_1 (\eta_2^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_1^x \\ &\quad + 2(\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \underline{\underline{e}}_2 \underline{\underline{e}}_2^T + 4 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1 \underline{\underline{e}}_1^T - 4\eta_1 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T \underline{\underline{e}}_1^x \\ &\quad - 2(\eta_2^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2) \underline{\underline{e}}_2^x - 4\eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1 \underline{\underline{e}}_1^T + 4\eta_1 \eta_2 \underline{\underline{e}}_2^x \underline{\underline{e}}_1^x \end{aligned}$$

$$C_{ca} = \underbrace{[1\eta_2^2 - \underline{\underline{e}}_2^T \underline{\underline{e}}_2] \mathbb{I}_3 + 2 \underline{\underline{e}}_2 \underline{\underline{e}}_2^T - 2\eta_2 \underline{\underline{e}}_2^x}_{C_{cb}} \underbrace{[(\eta_1^2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_1) \mathbb{I}_3 + 2 \underline{\underline{e}}_1 \underline{\underline{e}}_1^T - 2\eta_1 \underline{\underline{e}}_1^x]}_{C_{ba}} = C_{cb} C_{ba}$$

Thus, if  $\theta_3 = 180^\circ$  and  $\underline{\underline{e}}_3 = \eta_2 \underline{\underline{e}}_1 + \eta_1 \underline{\underline{e}}_2 + \underline{\underline{e}}_1^x \underline{\underline{e}}_2$  we obtain the same rotation  $C_{cb} C_{ba}$ .

Finally, if  $\theta_3 = 0^\circ$ , then no rotation occurs. In this case, every axis is the Euler axis. Hence, we can select  $\underline{\underline{e}}_3 = \eta_2 \underline{\underline{e}}_1 + \eta_1 \underline{\underline{e}}_2 + \underline{\underline{e}}_1^x \underline{\underline{e}}_2$ .

### Conclusion:

If  $(\underline{\underline{e}}_1, \eta_1)$  are the Euler symmetric parameters that describe the rotation from  $\underline{\underline{e}}_a$  to  $\underline{\underline{e}}_b$ , and  $(\underline{\underline{e}}_2, \eta_2)$  are the Euler symmetric parameters that describe the rotation from  $\underline{\underline{e}}_b$  to  $\underline{\underline{e}}_c$ , then the Euler symmetric parameters  $(\underline{\underline{e}}_3, \eta_3)$  that describes the rotation from  $\underline{\underline{e}}_a$  to  $\underline{\underline{e}}_c$  can be computed by:

$$\begin{aligned} \eta_3 &= \eta_1 \eta_2 - \underline{\underline{e}}_1^T \underline{\underline{e}}_2 \\ \underline{\underline{e}}_3 &= \eta_2 \underline{\underline{e}}_1 + \eta_1 \underline{\underline{e}}_2 + \underline{\underline{e}}_1^x \underline{\underline{e}}_2 \end{aligned}$$

Notice that no trigonometric function is required, and that we only need to store 4 parameters. Furthermore, the number of operations (multiplication and sum) to compose a rotation is lower than that required by the DCMs.